

Open-cut Proximity Detection & Underground Collision Avoidance

Neville McAlary
Senior Vice President
Safety and Training



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Overview

1. What are these two technologies
2. The case for change
3. Peabody trial and learning's
 - SafeMINE
 - Surface CAS System
4. UG proximity detection
5. History + working group
 - Two significant stall points
 - Current trials
 - Thermal imaging
6. Future state and issues



CASE FOR CHANGE – Open-cut

1. Fatalities in Australia
2. Near misses within Peabody AU
3. Equipment damage costs



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CASE FOR CHANGE – Open-cut

Ravensworth
30 November, 2013



Mt Arthur Mine – 18 October, 2013



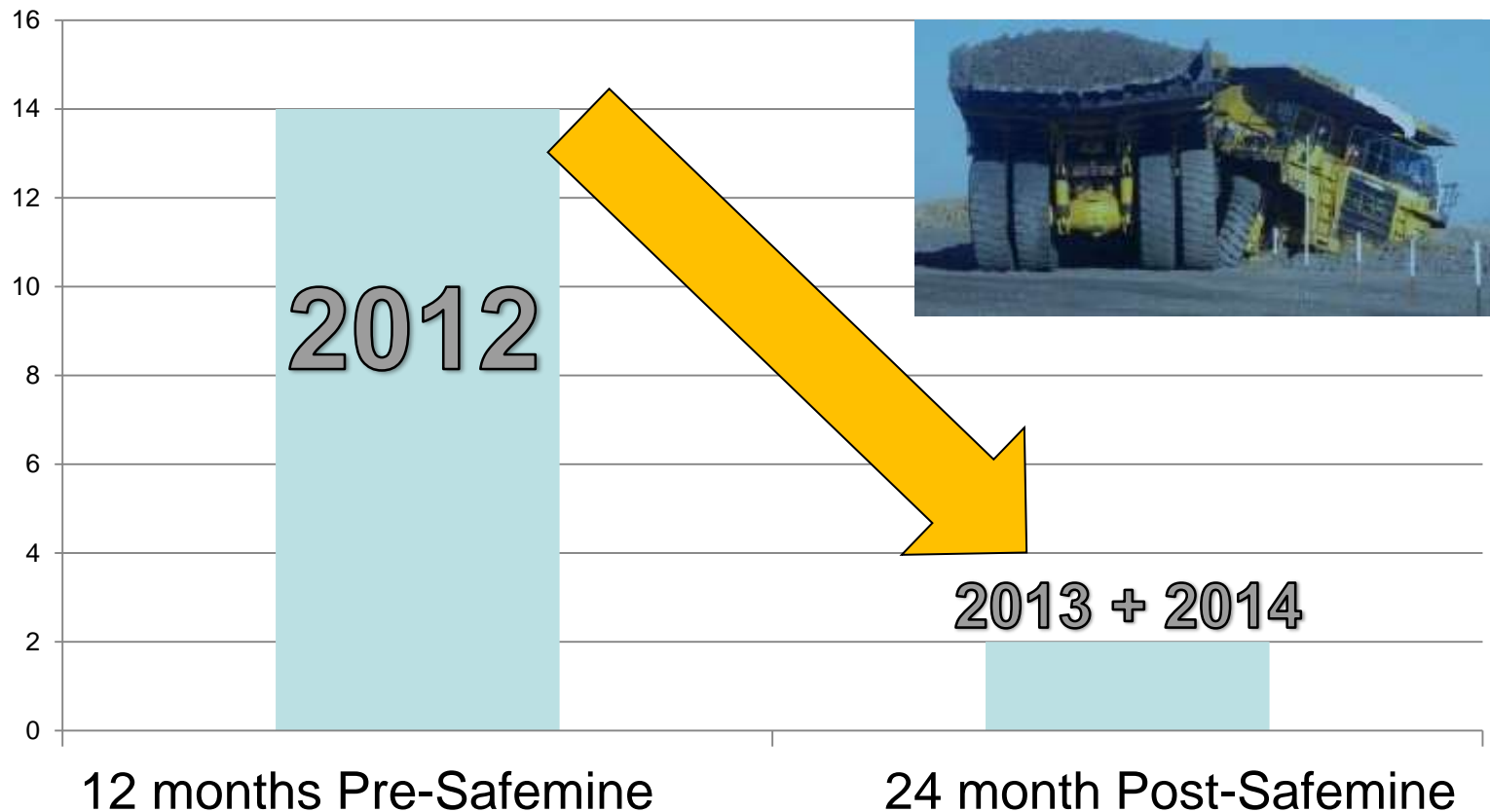
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Safemine – Burton & Millennium



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Burton 'SafeMINE' Collision Avoidance Trial

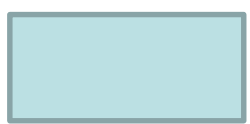
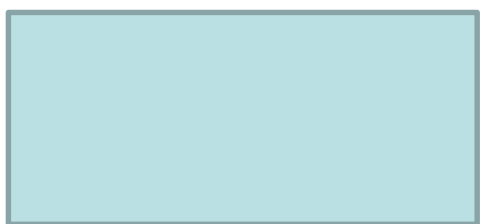
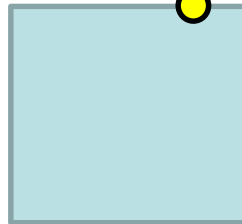
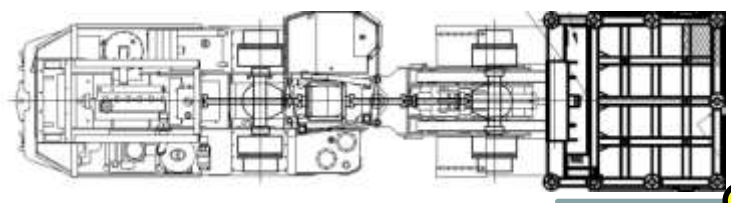


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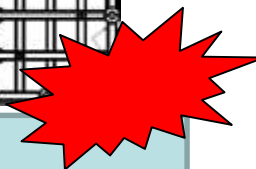
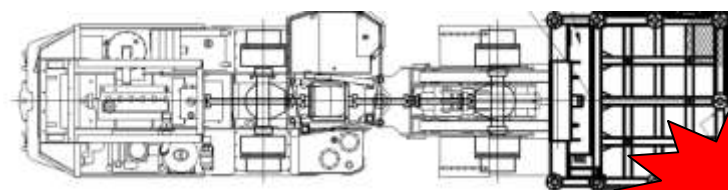
CASE FOR CHANGE - Underground

1. Fatalities at Peabody US operations
2. Fatality in Australian industry
 - Operator found under LHD NSW 2014
 - Moranbah North Coal 9 April, 2007
3. Significant Incidents within Peabody Australia
 - NGC - 30th June, 2010
 - [Wambo - 5 December, 2013](#)
 - [NGC - 25th June, 2014](#)



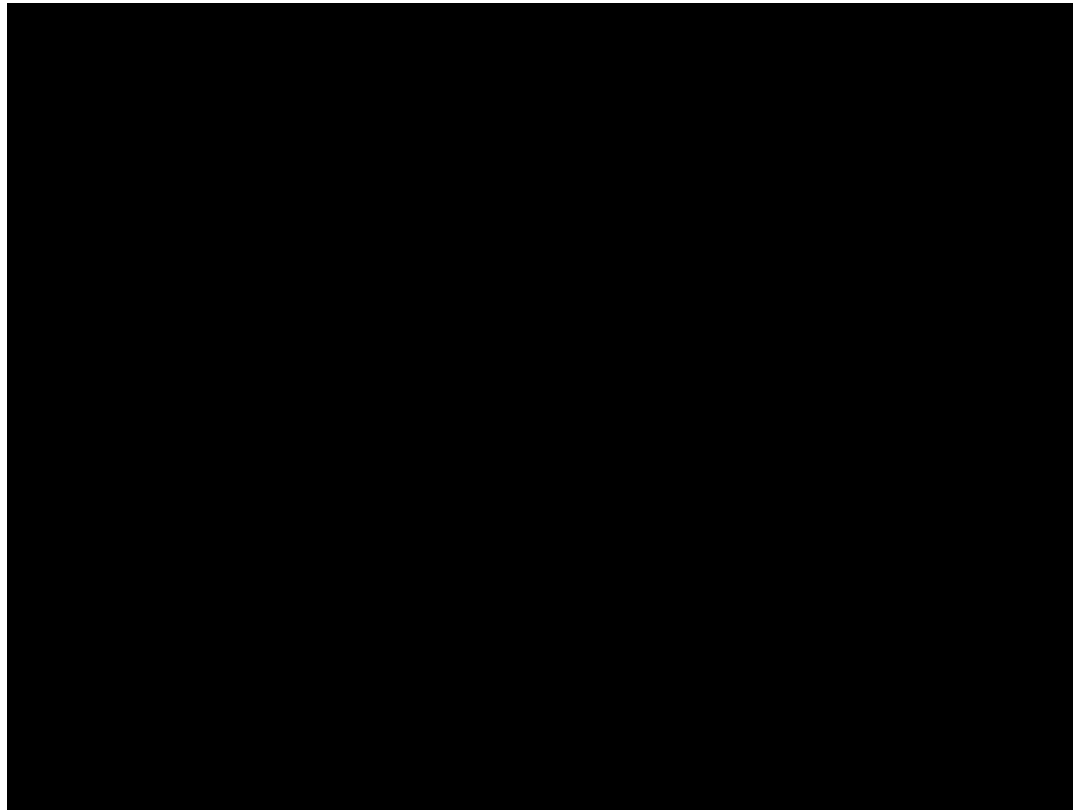






Wambo

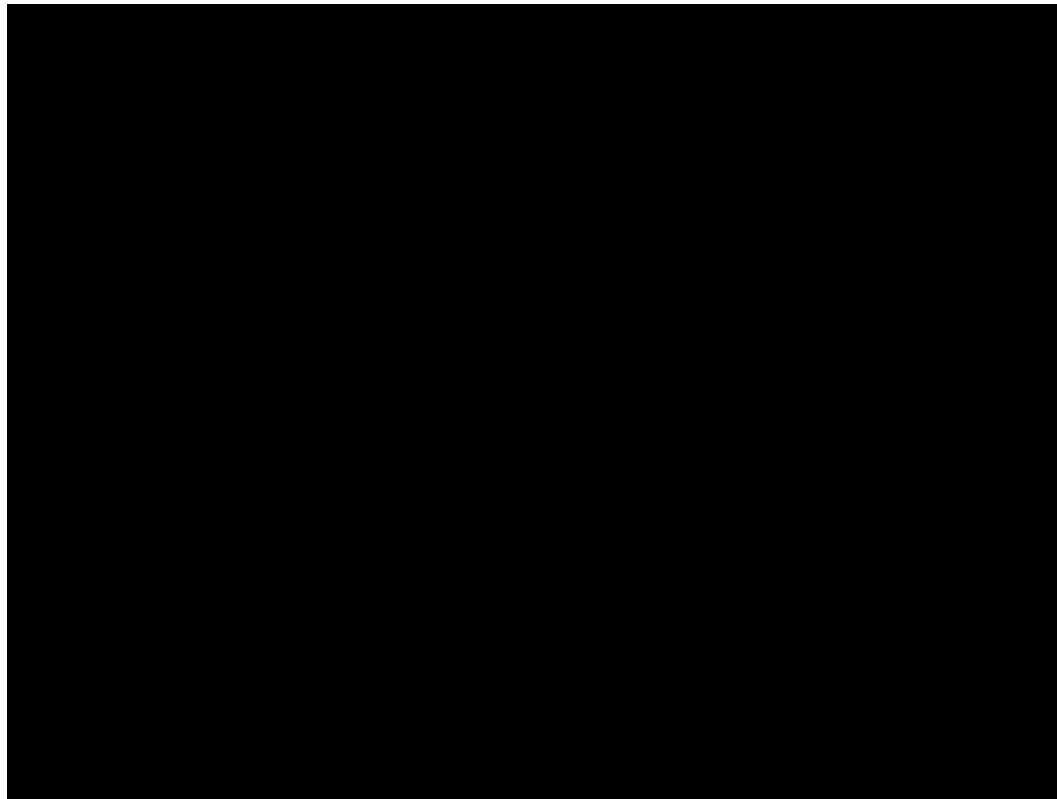
5th December, 2013



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North Goonyella

25th June, 2014



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History + Peabody Working Group

2010-11

- Started both open-cut proximity detection and underground collision avoidance projects and taskforces
- Visited mines in South Africa and United States with collision avoidance system

2012 – current

- Started full working trial of open-cut collision avoidance system 'SafeMINE' at Burton Mine in Queensland

2011-13

- Surface and NERZ zone trials of MST/Strata underground collision avoidance system at Joy Parkhurst and North Goonyella Mine

2014

- Selection of GE Collision Avoidance System to trial in working development panel of Metropolitan Mine
- Alert mode, prior to moving to shut-down



Two Significant Stall Points

1. Initially some suppliers stated UG proximity detection system could be intrinsically safe
 - Technology aspirations led detailed engineering reviews
 - Power draw for accuracy of system was beyond IS capacity
 - All suppliers now agree flameproof enclosure required for power source
2. Operators want interface with equipment logic
 - Machine changes mode as pedestrians detected at different distances
 - OEM interfaces are complex and proprietary
 - STOP machine and change behaviour

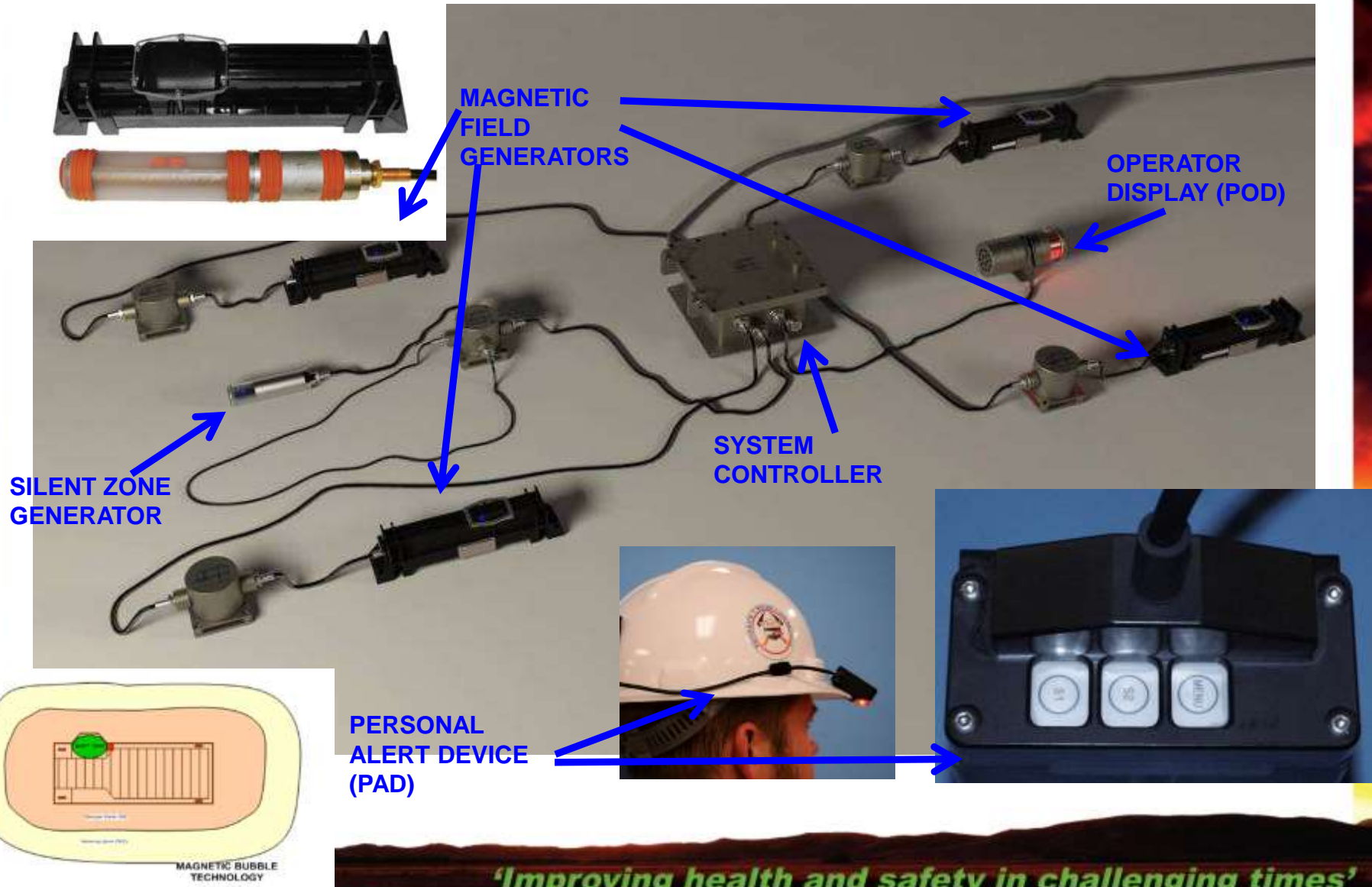


Metropolitan Development Panel Trial

- Continuous Miner and Shuttle Car
 - Tags in cap lamps
 - Enclosure approved
- Commencement - November 2014
- Design risk assessment and data acquisition to support SIL requirements of MDG 2007
 - Initially alert mode and record of pedestrian interactions
 - Final move to halt mode when system proven

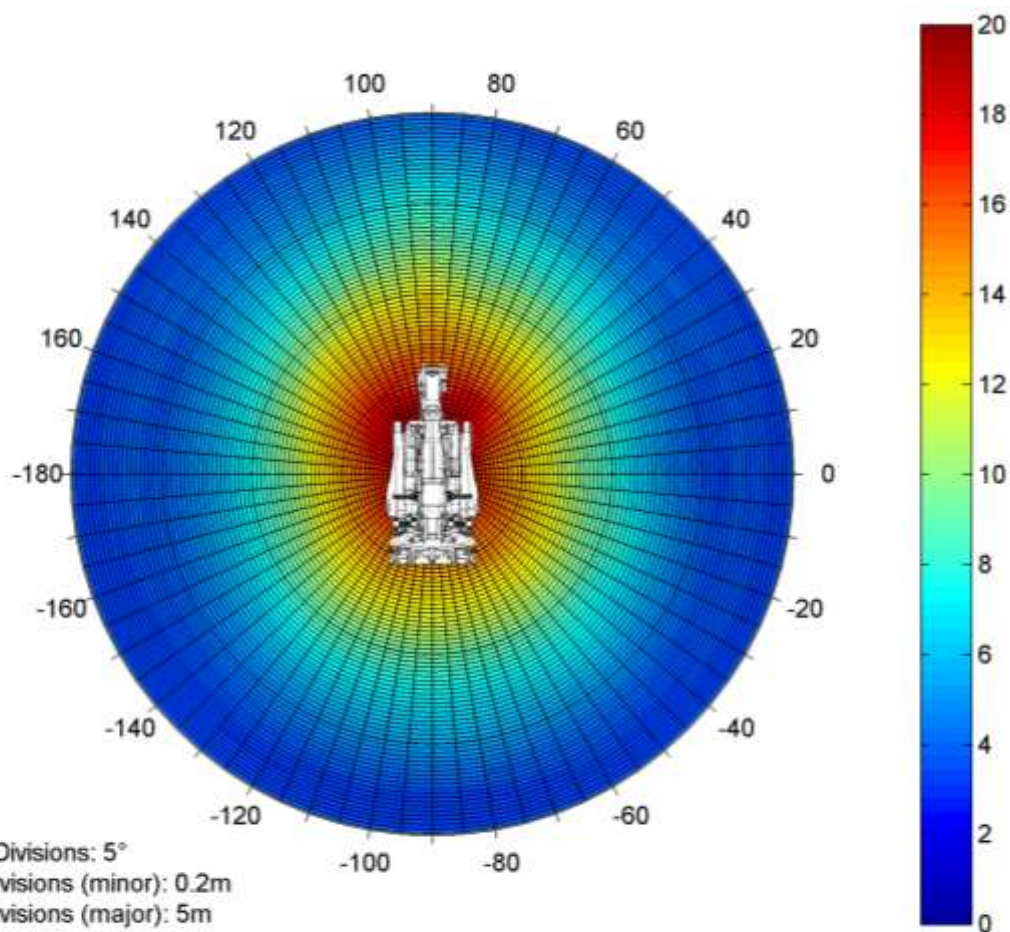


U/G System Components

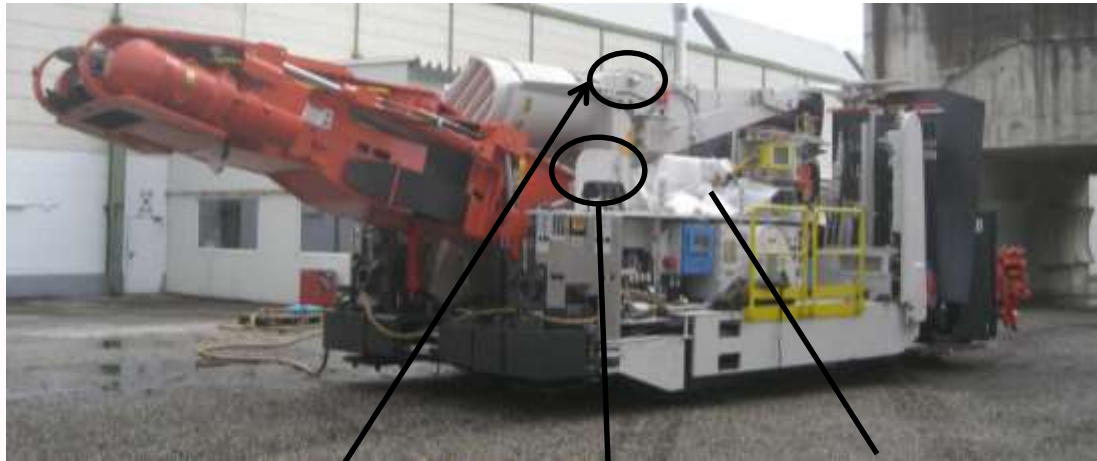


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Magnetic field map



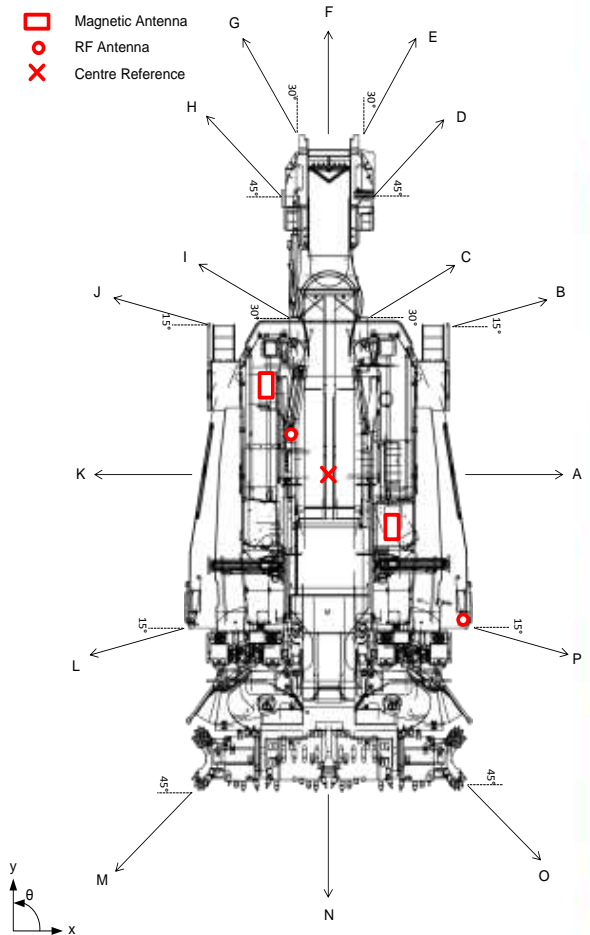
Machine Setup



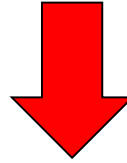
RF antenna

Magnetic antenna

Control &
Interlock Interfaces



Antenna Location



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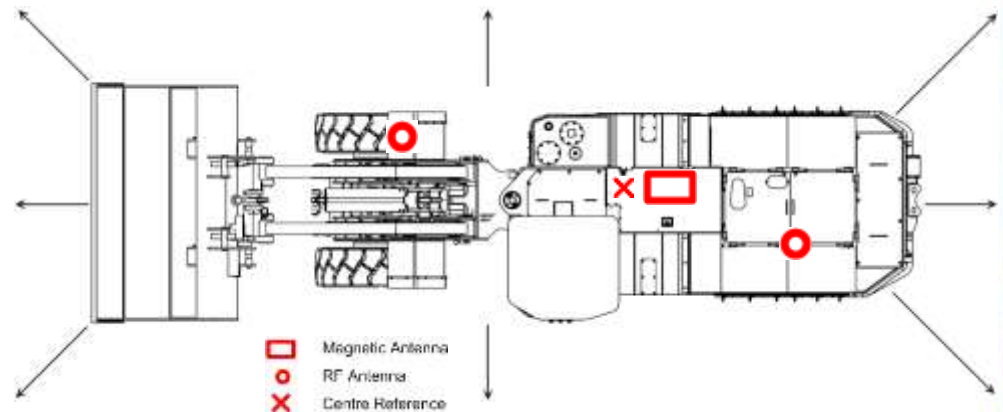
Machine Setup

Magnetic antenna

Controller



RF antenna





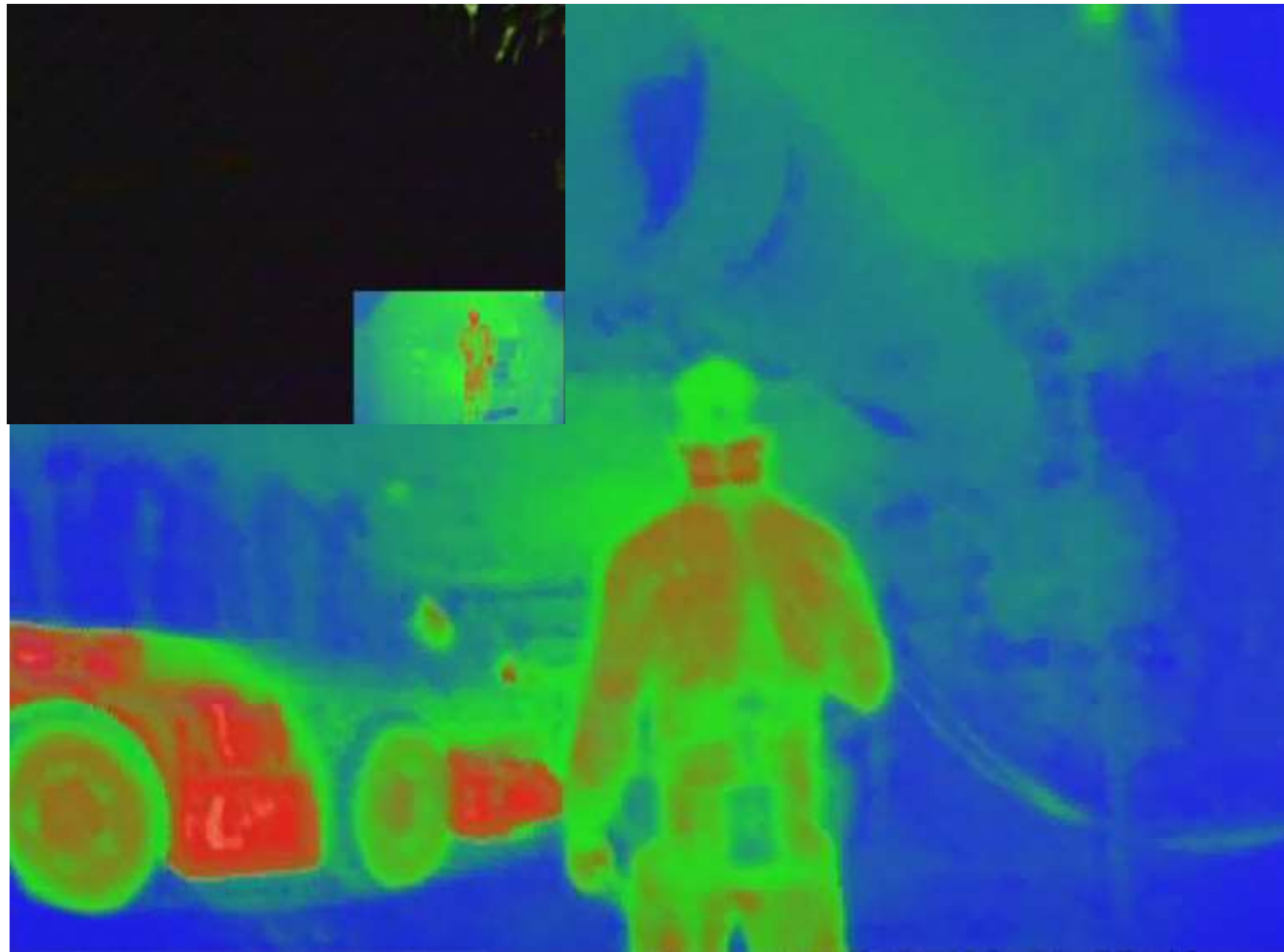
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Underground Collision Avoidance

- People in very close proximity to machinery is a real concern
- Fitting of Collision Avoidance Systems on underground mobile equipment is progressing, albeit slower than expected
- Trial underway on a shuttlecar at Myuna Colliery
- Peabody fitting out a working panel for trial
- ACARP trials of all systems planned to be approved in next two years
- Need to focus on taking small steps to help industry progress forwards...we were stuck
- Interaction between OEM systems is still an issue



Thermal Imaging – S/Car and LHD



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Thermal Imaging

- Installed on S/car at Metropolitan June 2014
- Operator acceptance was high
 - Vision in blind spots
 - Diluted traditional issues
 - Poor area lighting
 - Dust
 - Sprays
 - Through brattice capability
- Implementing on a LHD at NGC
 - Need to view in front of QDS device
 - Large Cable Reels and Loaded Cookie Plates

Video recognition of pedestrian and link to equipment operating mode?



Future State and Issues

- **UG Proximity - State of Mind**
 - Safety net versus front line tool
 - Psychological studies
 - Operator acceptance
 - Tagging – safety versus performance monitoring
- **CAS – Surface Mining**
 - Whole of fleet
 - System, configuration and logic
 - Fatigue monitoring and management

**OEM – Proprietary
systems integrated
with other equipment**

